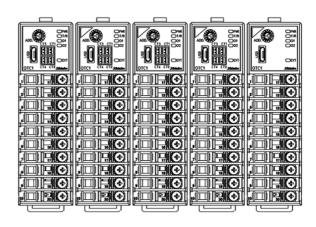
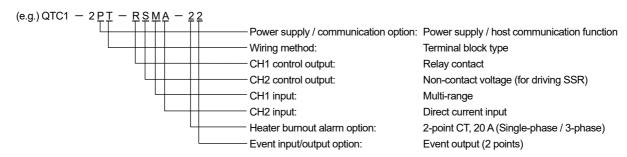
# **Control Module (2ch)**

Model: QTC1-2





#### **■** Model



QTC1—2										
Power	0								No options	
supply /	Р								Power supply / host communication function	
communica										
tion options										
Wiring metho	d	Т							Terminal block type	
CH1 control of	output								Con output and a table	
CH2 control of	output								See output code table	
CH1 input									One import and a table	
CH2 input									See input code table	
					-0		No options			
Heater burnout alarm options							-2		2-point CT, 20 A (Single-phase / 3-phase) (*1)	
			-A		2-point CT, 100 A (Single-phase / 3-phase) (*1)					
								0	No options	
Event input/output options								1	Event input (2 points) (*2)	
								2	Event output (2 points) (*2)	

- (\*1) CT and connector harness are sold separately.
- (\*2) Connector harness is sold separately.

## Output Codes

Code	Output Type
R	Relay contact output
S	Non-contact voltage output
	(for driving SSR)
Α	Direct current output, 4 to 20 mA DC
0	Direct current output, 0 to 20 mA DC
V	DC voltage output, 0 to 1 V DC
1	DC voltage output, 0 to 5 V DC
2	DC voltage output, 1 to 5 V DC
3	DC voltage output, 0 to 10 V DC
С	Open collector output
Т	Triac output

## Input Codes

Code	In	put Type	Range	
		K	-200 to 1370°C	
		K	-200.0 to 400.0°C	
		J	-200 to 1000°C	
		R	0 to 1760°C	
		S	0 to 1760°C	
		В	0 to 1820°C	
		Е	-200 to 800°C	
		Т	-200.0 to 400.0°C	
		N	-200 to 1300°C	
		PL- II	0 to 1390°C	
		С	0 to 2315°C	
	Thermocouple	K	-328 to 2498°F	
		K	-328.0 to 752.0°F	
		J	-328 to 1832°F	
		R	32 to 3200°F	
М		S	32 to 3200°F	
		В	32 to 3308°F	
		Е	-328 to 1472°F	
		Т	-328.0 to 752.0°F	
		N	-328 to 2372°F	
		PL- II	32 to 2534°F	
		С	32 to 4199°F	
	DTD	Pt100	-200.0 to 850.0°C	
	RTD	Pt100	-328.0 to 1562.0°F	
	DC voltage	0 to 1 V DC	-2000 to 10000	
		4 to 20 mA DC		
		(Externally mounted	-2000 to 10000	
	Direct current	shunt resistor)		
	Direct current	0 to 20 mA DC		
		(Externally mounted	-2000 to 10000	
		shunt resistor)		
Α		4 to 20 mA DC	-2000 to 10000	
	Direct current	(Built-in shunt resistor)	2000 10 10000	
'`	2001 00110111	0 to 20 mA DC	-2000 to 10000	
		(Built-in shunt resistor)	2000 10 10000	
		0 to 5 V DC	-2000 to 10000	
V	DC voltage	1 to 5 V DC	-2000 to 10000	
		0 to 10 V DC	-2000 to 10000	

# ■ Accessories Sold Separately

Product Name	Model
50 Ω shunt resistor	RES-S01-050
Front terminal cover	TC-QTC
CT for 20 A	CTL-6-S-H (*1)
CT for 100 A	CTL-12-S36-10L1U (*1)
Heater burnout alarm connector harness	WQ (*1)
Event input/output connector harness	EVQ (*2)

<sup>(\*1)</sup> For heater burnout alarm (heater burnout alarm option symbols: -2, -A)

<sup>(\*2)</sup> For event input or event output (event input/output option symbols: 1, 2)

# ■ Rating

## Rated Scale

Input (TC)	Scale Range		Resolution	Input (RTD)	Scale	Range	Resolution
K	-200 to 1370°C	-328 to 2498°F	<b>1</b> ℃(°F)	Pt100	-200.0 to 850.0°C	-328.0 to 1562.0°F	0.1℃(℉)
K	-200.0 to 400.0°C	-328.0 to 752.0°F	0.1℃(℉)				
J	-200 to 1000°C	-328 to 1832°F	<b>1</b> ℃(°F)				
R	0 to 1760°C	<b>32 to 3200</b> °F	<b>1</b> ℃(°F)				
S	0 to 1760°C	32 to 3200°F	<b>1</b> ℃(°F)	Input (DC)	Scale	e Range	Resolution
В	0 to 1820°C	32 to 3308°F	<b>1</b> ℃(°F)	4 to 20 mA			
E	-200 to 800°C	-328 to 1472°F	<b>1</b> ℃(℉)	0 to 20 mA			
Т	-200.0 to 400.0°C	-328.0 to 752.0°F	0.1°C(°F)	0 to 1 V	2000 +	10000 (*)	4
N	-200 to 1300°C	-328 to 2372°F	<b>1</b> ℃(℉)	0 to 5 V	-2000 (0	7 10000 ( )	•
PL-II	0 to 1390°C	32 to 2534°F	<b>1</b> ℃(°F)	1 to 5 V			
С	0 to 2315°C	32 to 4199°F	<b>1</b> ℃(°F)	0 to 10 V			

<sup>(\*)</sup> Scalable

## Input

input		
Thermocouple (TC)	K, J, R, S, B, E, T, N, C (JIS C1602-2015), PL- II (ASTM E1751M-15)	
	External resistance: 100 $\Omega$ or less (However, B input: 40 $\Omega$ or less)	
RTD	Pt100, 3-wire type (JIS C1604-2013)	
	Allowable input lead wire resistance: $10 \Omega$ or less per wire	
Direct current (mA DC)	0 to 20 mA DC, 4 to 20 mA DC	
	Input impedance: 50 Ω (Shunt resistance)	
	Allowable input current: 50 mA or less	
DC voltage (V DC)	0 to 1 V DC	
	Input impedance: 1 MΩ or more	
Allowable input voltage: 5 V DC or less		
	Allowable signal source resistance:2 $k\Omega$ or less	
	0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
	Input impedance: 100 kΩ or more	
	Allowable input voltage: 15 V DC or less	
	Allowable signal source resistance:100 $\Omega$ or less	

## ■ Performance

Basic accura	су	At ambient temperature of 23°C and mounting angle of ±5 degrees					
	Thermocouple	Within ±0.2% of each input span					
		However, below 0°C (32°F): Within ±0.4% of each input span					
		R, S inputs, 0 to 200 $^{\circ}$ C (32 to 392 $^{\circ}$ F): Within ±6 $^{\circ}$ C (12 $^{\circ}$ F)					
		B input, 0 to 300°C (32 to 572°F): Accuracy is not guaranteed.					
	RTD	Within ±0.1% of each input span					
	Direct current	Within ±0.2% of each input span					
	DC voltage	Within ±0.2% of each input span					
Cold junction	temperature	Within ±1°C at -10 to 55°C					
compensation	n accuracy						
Effect of amb	ient temperature	Thermocouple input (no decimal point): Within ±100 ppm/C of each input span					
		Below 0°C (32°F): Within ±200 ppm/°C of each input span					
		Thermocouple input (decimal point): Within ±200 ppm/C of each input span					
		Below 0°C (32°F): Within ±400 ppm/°C of each input span					
		Other: Within ±100 ppm/°C of each input span					
Effects of elec	ctromagnetic	Within ±1% of each input span					
interference							
Input sampling period		20 ms (with only DC voltage input and direct current input enabled)					
		50 ms (with only DC voltage input and direct current input enabled)					
		125 ms					
		Note: Fixed to 125 ms regardless of settings for thermocouple input and RTD input					

# **■** Control Performance

Control action		Control method selectable from 2	DOF PID co	ontrol, Fast-PID control, Slow-PID control, ON-OFF control, c			
		Gap-PID control. For optimal control, select the best control method according to the intended use and					
		process.					
		(Factory default: 2DOF PID contro	l)				
2DC	OF PID control	2DOF PID control					
Fas	st-PID control	A control method that offers both tracking characteristics with SV changes, and disturbance suppressio					
	w-PID control	This method offers the same disturbance responsiveness as Fast-PID control as well as control action					
Gar	o-PID control	with reduced overshooting.  Fast-PID control  This general PID control method is used for constant value control (SV control at a single value).					
3.54							
		P control: When integral tin	ne and deriv	vative time are set to 0.			
		<ul> <li>PI control: When derivative</li> </ul>	time is set	to 0.			
		<ul> <li>PD control: When integral t</li> </ul>	ime is set to	0.			
		<ul> <li>Deviation PID control: When</li> </ul>	n the propor	tional gain 2DOF coefficient ( $lpha$ ) is set to 1.00 and the derivative			
		2DOF coefficient ( $\gamma$ , Cd)	is set to 1.0	0.			
		Slow-PID control					
		This control method is effective	for process	ses where generating overshoot is not desired, and processe			
		where the PV does not easily d					
		Gap-PID control		3			
		If the PV is noisy or if there is hysteresis in the operation unit, a slight fluctuation may be maintained nea					
		•	-	band is usually used, but since control is not performed with			
				nt of a disturbance. In this way, this control method ensure			
		deviation characteristics in dead bands and allows for disturbance responses.					
		Item		Setting Range			
		Proportional band (P)		1 to Input span °C (°F) or 0.1 to Input span °C (°F)  Direct current input, DC voltage input: 0.10 to 100.00%  0 to 3600 sec or 0.0 to 2000.0 sec			
		, ,					
		Integral time (I)					
		,		1 to 3600 sec or 0.1 to 2000.0 sec (When Slow-PID control			
				is selected)			
				The setting range varies depending on the selected			
				integral/derivative decimal point position.			
		Derivative time (D)		0 to 3600 sec or 0.0 to 2000.0 sec			
		Benvalive line (B)		The setting range varies depending on the selected			
				integral/derivative decimal point position.			
		Proportional gain 2DOF coeffic	piont ( a)	0.00 to 1.00			
			cient (a)				
		Integral 2DOF coefficient (β)	0.11	0.00 to 10.00			
		Derivative 2DOF coefficient ( γ	′, Cd)	0.00 to 1.00			
		Proportional cycle		0.1 to 100.0 sec			
		Output high limit, output low lin	nit	0.0 to 100.0%			
				Direct current output: -5.0 to 105.0%			
		Gap width (*)		0.0 to 10.0%			
				Proportional band × Gap width			
		Gap coefficient (*)		0.0 to 1.0			
		(*) With Gap-PID control only					
ON–OFF control		Control method that operates with only two va		alues: ON and OFF			
		Item		Setting Range			
				00.0℃ (0.1 to 1800.0℉)			
		'		rrent input, DC voltage input: 1 to 10000			
Control range							
		Control output is turned OFF when the following control ranges are exceeded.					
		Thermocouple input (no decimal point)					
		Input range low limit value -50°C (90°F) to Input range high limit +50°C (90°F)					
		Thermocouple input (decimal point), RTD input					
			-	%) $^{\circ}$ C (F) to Input range high limit + 50.0 $^{\circ}$ C (90.0 $^{\circ}$ F)			
		Direct current input, DC voltage inp					
		Scaling low limit value - Scaling	width × 1%	to Scaling high limit value + Scaling width × 10%			

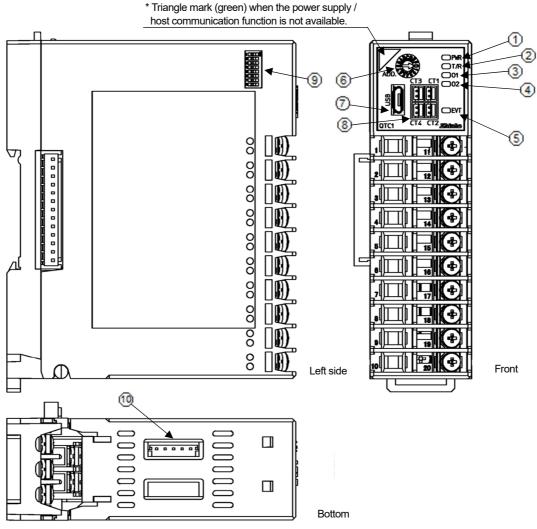
Control output	Relay contact output:	1a					
		Control capacity:3 A 250 V AC (resistive load)					
		1 A 250 V AC (inductive load $\cos \varphi = 0.4$ )					
		Electrical life: 100,000 cycles					
		Minimum applicable load: 10 mA 5 V DC					
	Non-contact voltage output	12 V DC ± 15%					
	(for driving SSR)	Max. 40 mA (short circuit protected)					
		* The power supply is not electrically insulated from the output.					
	Direct current output	4 to 20 mA DC, 0 to 20 mA DC (Resolution: 12000)					
		Load resistance: Maximum 550 $\Omega$					
		* The power supply is not electrically insulated from the output.					
	DC voltage output:	0 to 1 V DC, 0 to 5 V DC, 1 to 5 V DC, 1 to 10 V DC (Resolution: 12000)					
		Allowable load resistance: 1 kΩ or more					
		* The power supply is not electrically insulated from the output.					
	Open collector output (NPN):	Allowable load current:100 mA or less					
		Load voltage: 30 V DC or less					
	Triac output:	Allowable load current: 0.5 A or less					
	(AC output zero-cross method)	Load voltage: 75 to 250 V AC					

## **■** General Structure

Weight		Approx. 150 g				
Dimensions		$30 \times 100 \times 85 \text{ mm} (W \times H \times D) \text{ (excl. protrusions)}$				
		Depth with terminal cover attached: 95 mm				
Mounting meth	od	DIN rail mounting				
Case material,	color	Case material: Flame-resistant resin, Color: Black				
Panel		Polycarbonate sheet				
Standards (*)	EN	EN61010-1 (Pollution degree 2)				
	EC	EMI: EN61326				
(EMC directive)		Electric-field strength of radiated disturbance: EN55011 Group 1, Class A				
		Terminal noise voltage: EN55011 Group 1, Class A				
		EMS: EN61326				

 $<sup>(\</sup>sp{*})$  Triac output specifications are not applied to each standard.

# ■ Indication Structure / Settings Structure



#### Action Indicator

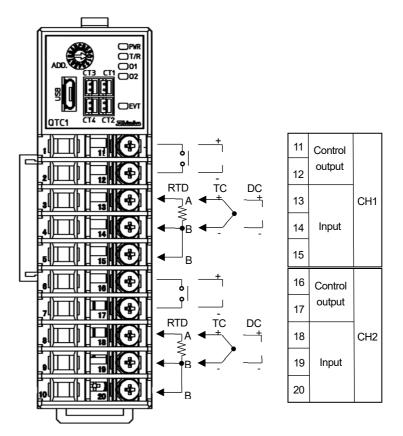
Action if	luicatoi				
No.	Symbol (color)	Name, Task		Symbol (color)	Name, Task
	PWR	Power indicator	3	O1 (green)	CH1 control output indicator
	(green)	Off: No power supplied to module		O2 (green)	CH2 control output indicator
1		On: Power supplied to module		EVT (red)	Event indicator
		Flashing: Internal error during warm-up			Lights up when an alarm is activated, a loop
		(Non-volatile memory, ADC input circuit)			break alarm is activated, or a heater burnout
	T/R	Communication indicator	(5)		alarm (optional) is activated.
	(yellow)	Flashing: Normal communication, Communication			Flashes in the event of a sensor error or
2		error (reception error)			overscale/underscale.
		Off: Communications error (no response), USB			
communication					

## Switches, Connectors

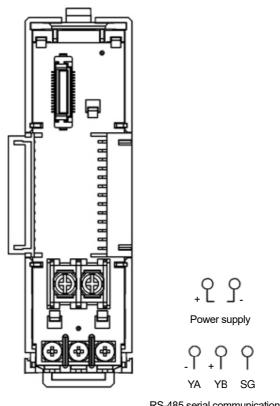
WILCINES, COI	II ICOLOI S						
No.	Symbol	Name, Task					
6	ADD.	Rotary switch for module address selection					
		Use the rotary switch to select the module address from 0 to F (1 to 16).					
7	USB	Micro USB Type-B console communication connector					
	CT1	CH1 CT input connector					
<b>8</b> (*1)	CT2	CH2 CT input connector					
<sup>(8)</sup> (*1)	CT3	CH3 CT input connector (for Ch1 3-phase)					
	CT4	CH4 CT input connector (for Ch2 3-phase)					
9	DIP switches for selecting communications specification						
		Use the DIP switches for selecting the communication speed, data bit, parity, stop bit, and communication protocol.					
10 (*2)		Event input/output connector					

- (\*1) When using the heater burnout alarm option (heater burnout alarm option symbols: -2, -A)
- (\*2) When using the event input or event output option (event input/output option symbols: 1, 2)

# ■ Terminal Arrangement QTC1-2PT-



Front



RS-485 serial communication (\*)

Base

(\*) The QTC1-20 do not include a Power supply terminal and RS-485 serial communication terminal.

## **■** Standard Functions

#### Alarm Output

	40.1	
Alarm types	12 alarm types: High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limit range alarm, Process high alarm,	
	Process low alarm, High limit with standby alarm, Low limit with standby alarm, High/Low limits with standby alarm,	
	High/Low limits independent alarm, High/Low limit range independent alarm, High/Low limits with standby independent	
	alarm. No alarm action can also be selected. (Factory default: No alarm action)	
Action	ON/OFF action	
Hysteresis	0.1 to 1000.0°C (0.1 to 1800.0°F) (Factory default: 1.0°C (1.8°F))	
	Direct current, DC voltage input: 1 to 10000 (Factory default: 10)	
Output	Event output assigned by status flag or event output assignment selection	
Alarm value 0	If "Enabled" is selected in [Alarm value 0 Enabled/Disabled], the following alarm type activates even if the alarm value is	
Enabled/Disabled	set to 0 (zero): High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limit range alarm, High limit with standby	
	alarm, Low limit with standby alarm, High/Low limits with standby alarm, High/Low limits independent alarm, High/Low	
	limit range independent alarm, High/Low limits with standby independent alarm.	

#### Loop Break Alarm

Setting range	Loop break alarm time:	0 to 200 minutes		
	Loop break alarm action span:	Thermocouple, RTD inputs:	0 to 150°C	(0 to 270 °F) or 0.0 to 150.0 °C (0.0 to 270.0 °F)
		Direct current, DC voltage input:	0 to 1500	
Output	Event output assigned by status flag or event output assignment selection			

#### Set Value Ramp Function

When changing SV, this function enables control at the specified change rate between the previous SV and the changed SV rate.					
When control is e	When control is enabled, control is performed at the specified change rate between the current PV and the SV.				
Setting range	ng range SV rise rate: Thermocouple, RTD inputs: 0 to 10000°C/minute (0 to 18000°F/minute) or		0 to 10000°C/minute (0 to 18000°F/minute) or		
			0.0 to 1000.0°C/minute (0.0 to 1800.0°F/minute)		
		Direct current, DC voltage input:	0 to 10000/minute		
	SV fall rate:	Thermocouple, RTD inputs:	0 to 10000°C/minute (0 to 18000°F/minute) or		
			0.0 to 1000.0°C/minute (0.0 to 1800.0°F/minute)		
		Direct current, DC voltage input:	0 to 10000/minute		
	The factory default for both the SV rise rate and SV fall rate is 0. However, when set to 0, this function is disabled.				

#### Power-On Return Action Selection

Select whether to return to a continued state (state before the power was turned off) or in the stopped state after the power is turned on.

## Non-Volatile IC Memory Data Save Selection

Selecting whether to allow or prohibit saving data to the non-volatile IC memory is possible.

If saving is prohibited, all setting values can be changed temporarily until the power is turned off and back on, at which time the values will return to the values applied before saving was prohibited.

#### Automatic/Manual Control Switching

Switching between automatic and manual control is possible through host communication.

#### Sensor Correction Coefficient

Setting the sensor input va	alue slope is possible.	
Setting range	0.000 to 10.000 (Factory default: 1.000)	

#### Sensor Correction

If the control location temperature and the sensor location temperature are different, shifting and correction of the PV is possible.			
(Valid within the rated input range regardless of the sensor correction value.)			
Setting range Thermocouple, RTD inputs: -100.0 to 100.0°C (-180.0 to 180.0°F)		-100.0 to 100.0℃ (-180.0 to 180.0℉)	
	Direct current, DC voltage input:	-1000 to 1000	

#### Control Function Selection

Selecting between standar	Selecting between standard control, heating/cooling control, cascade control, or output selection function is possible.		
Cascade control	The master-side operation output amount obtained from the master-side SV and PV (CH1) is substituted for the		
	slave-side SV (CH2), slave-side calculation is performed, and the slave-side control output is output. (With CH1		
	control output OFF (Current output: 0 mA))		
Heating/cooling control	When heating/cooling control is selected as the control function for CH1, heating/cooling control is performed with		
	CH1 as the heating side output and CH2 as the cooling side output. Heating/cooling control cannot be selected for		
	CH2.		
Output selection function	When using the controller, if there is an unused input and an error occurs in the input channel currently being used,		
	the input can be changed to an unused channel, and the output location for the input can be selected.		

#### **Extension Function Selection**

Selecting between no extension, Peak power suppression function and the auto-balance control function is possible.		
Peak power suppression function	A function to suppress the peak power value when there is a power limit for the facility. The total current	
	can be set, and power suppression control can be performed when the sum of the current values set for	
	each channel is less than or equal to the total current. *(Disabled when Direct current output or DC voltage	
	output are selected, and each set value change is effective only when control is stopped.)	
Auto-balance control function	This function controls the temperature of a controlled object at multiple control points to suppress partial	
(For devices with power supply /	burning and mechanical distortion.	
host communication function)	There are two auto-balance control types: using multiple control modules, or using independent control	
	modules.	

#### Output Gain/Bias Function

When multiple outputs are used for inputs, such as input-based heater controls at multiple outputs, if the output amount distribution is known in advance, this function enables uniform control by setting the ratio and bias for the reference output.

#### Input Calculation Function

Input calculation function selection can be used to select between standard input, difference input, and addition input.

The calculation function selected for CH1 applies to CH1 and CH2. However, the selection becomes invalid if a non-standard control function is selected

#### Input Difference Detection Function

The input difference between the current input difference detection selection channel and the selected channel is detected, and if the value set in the input difference detection setting is exceeded, 1 is set as the input difference flag. However, if the current input difference detection selection channel is selected, this function is disabled.

## ■ Optional Functions

Heater Burnout Alarm (Heater burnout alarm option symbols: -2, -A)

This function cannot be added to Direct current output, DC voltage output or Triac output type. The status can be determined by reading the			
status flag during serial communication	status flag during serial communication.		
Rating Single-phase/3-phase: 20 A, Single-phase/3-phase: 100 A (specified when ordering)			
Setting range	20 A: 0.0 to 20.0 A (Off when set to 0.0)		
	100 A: 0.0 to 100.0 A (Off when set to 0.0)		
Setting accuracy	±5% of rated value		
Action point	Set value		
Action	ON/OFF action		
Output	Event output selected by status flag or event output assignment selection		

#### Event Input (Event input/output option symbol: 1)

When an event input is input, the operations selected by the event input assignment selection are performed.			
Event input assignment selection No action, Control start/stop (CH independent), Control start/stop (CH interlock)			
No. of inputs	2		
Input method	Voltage contact input sink method		
Circuit current when closed Approx. 6 mA			
Reading judgment time Approx. 100 ms			

#### Event Output (Event input/output option symbol: 2)

The operations selected by the event output assignment selection are performed.			
Event output assignment selection No action, EVT output (CH independent), EVT output (CH interlock)			
No. of outputs 2			
Circuit	NPN open collector		
Maximum load voltage	30 V DC		
Maximum load capacity	50 mA		

Power Supply / Host Communication Function (Power supply/communication option symbol: P)

Communication line	EIA RS-485 compliant			
Communication method	Half-duplex communication			
Communication speed	Selecting 9600, 19200, 3840	00, or 57600 bps is possible using t	the DIP switches. (Factory default: 57600 bps)	
Synchronization method	Start-stop synchronization			
Data bit/parity	Data bits: 8			
	Parity: Selecting eve	en, odd, or no parity is possible usir	ng the communication specification selection	
	DIP switch. (Factory default: 8 bits / Even)			
Stop bit	Selecting 1 or 2 is possible using the communication specification selection DIP switch. (Factory default: 1)			
Response delay time setting	0 to 1000 ms (Factory default: 0 ms)			
The response from the module after receiving a command from		n the host can be delayed.		
Data structure			1	
	Communication protocol	MODBUS RTU		
	Start bit	1		
	Data bit	8		
	Parity	Enabled (even, odd), Disabled		
	Stop bit	1 or 2		
		·		

Smart InterFace (SIF) Function (Program-less communication function)

This function enables a serial communication connection with Mitsubishi Electric MELSEC-Q series PLCs and writes/reads various data to/from the PLC register using the PLC communication protocol.

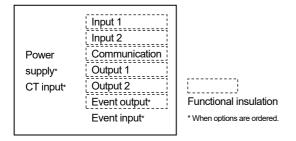
The communication protocol uses QW and QR commands, and PLCs capable of using A-compatible 1C frame AnA/AnU common commands (QR/QW) (D resister) are supported.

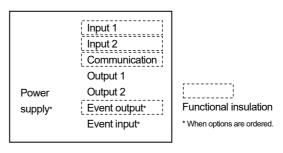
#### ■ Insulation / Dielectric Resistance

Circuit Insulation Configuration

· Relay output, Open collector output, Triac output

 $\cdot$  Non-contact voltage output, Direct current output, DC voltage output





Insulation resistance	500 V DC, 10 MΩ or more	
Dielectric resistance	Between input terminal and ground:	1.5 kV AC for 1 minute
	Between power terminal and ground:	1.5 kV AC for 1 minute
	Between power terminal and input terminal:	750 V AC for 1 minute

#### **■** Environmental Conditions

Ambient temperature	-10 to 55°C (Non-condensing, no icing)	
Ambient humidity	35 to 85% RH (Non-condensing)	
Environmental specifications	Compliant with revised RoHS Directive (RoHS2)	

# **■** Attached Functions

Power failure countermeasures	Setting data is backed up to non-volatile IC memory.			
Self-diagnosis			the CPU, and if an error occurs, all outputs are turned OFF and the	
	instrument is initialized.			
Automatic cold junction temperature	Detect the temperature at the connection terminal between the thermocouple and the instrument is			
Compensation	detected and adjusted to be the same as if the reference contact were always at 0°C (32°F).			
, , , , , , , , , , , , , , , , , , ,	(Valid only for channels for which thermocouple input is selected)			
PV filter time constant setting	A digital first-order low-pass filter is used to reduce PV fluctuations caused by noise.			
Moving average count setting	Values that alter input values due to noise are averaged to stabilize the indicated values.			
CH enable/disable selection	Enabled or disabled can be selected for each channel.			
	When disabled, all operations for the selected channel are disabled, and PV becomes 0.			
Overscale	A status flag is set when overscale is detected. However, control continues during overscale.			
Underscale	A status flag is set when underscale is detected. However, control continues during underscale.			
Sensor error	A status flag is set when a sensor error is detected, and control output is turned OFF.			
Cold junction error	A cold junction error occurs when the internal cold junction temperature is below -10°C (14°F) or above			
•	55°C (131°F).			
	(Valid only for channels for which thermocouple input is selected)			
ADC error	If there is an error such as a failure in an internal circuit, the control output of the channel where the			
	error occurred is turned OFF.			
	When this occurs, the PV is 32767.			
Warm-up display	After the power is turned on, the power indicator flashes every 500 ms for about 3 seconds.			
Cumulative contact open/close count	Cumulative measurement of the control output ON/OFF count is possible.			
measurement function				
Cumulative energization time	Checking the cumulative energization time is possible.			
measurement function				
Cumulative heater energization time	Checking the cumulative heater energization time is possible for relay output and SSR output.			
measurement function				
Error history	In the event of an error, the bit ON/OFF status and energization time are saved. The 10 most recent			
	errors are saved.			
	Error history is available for each channel, and device common errors are saved in the all-channel			
	error history.			
	Error details  Alarm 1, Alarm 2, Heater burnout alarm, Loop break alarm, Sensor error, Input error (overscale), Input error (underscale), Cold junction error, Non-volatile IC memory error, ADC error			
Canada	Connect a comm	u mination and	le (commercially quallable) to the concelle communication connector to	
Console communication	Connect a communication cable (commercially available) to the console communication connector to perform operation from an external computer using the console software (SWC-QTC101M).			
Communication	Operations that can be		(1) Reading and configuration of SV, PID, and various other setting	
	performed		values	
			(2) Reading of PV and operating statuses	
			(3) Modification of functions	
	Communication protocol		MODBUS RTU	
	Communication cable		USB to Micro USB Type-B (Commercially available)	
	Software		Console software (SWC-QTC101M)	
			, , ,	
Firmware update function	Connect the communication cable (commercially available) to the connector for console			
	communication and use the console software (SWC-QTC101M) to update the functions from an			
	external computer.			

# ■ Other

Power supply voltage	24 V DC Allowable fluctuation range: 20 to 28 V DC			
Power consumption	5 W or less			
Rush current	Max. 10 A			
Accessories included	Line cap (1), Power supply terminal cover (for devices with power supply / host communication function) (1),			
	Mounting and wiring instruction manual (1)			
Accessories sold	Shunt resistor (50 Ω) (RES-S01-050), Front terminal cover (TC-QTC), CT for heater burnout alarm 20 A (CTL-6-S-H),			
separately	CT for heater burnout alarm 100 A (CTL-12-S36-10L1U), Heater burnout connector harness (WQ), Event input/output			
	connector harness (EVQ)			
Instruction manual	Please download the full Instruction Manual from the Shinko website.			
	https://shinko-technos.co.jp/e/			

## **■** Dimensions (Scale: mm)

#### Main Unit

