**Programmable Controller** 

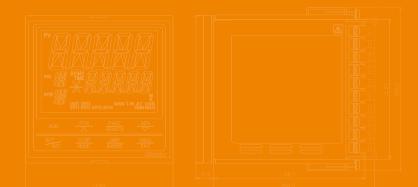


PCA1

# **Upgraded Model**Enhanced Performance and Functions



16-patterns 16-steps, A maximum of 256 programmable steps *Easy status checking using 3-color switching* 



Easy Setup with a USB Communication Cable (USB powered) Drip-proof / Dust-proof IP66 (front panel only)

# Model

(e.g.)	<u>PCA1 R 0 0- 210</u>
	Control output :Relay contact Power supply :100 to 240 V AC Input: Multi-range Option 1: Serial communication RS-485 Option 2: Transmission output (4 to 20 mA DC) Option 3: Option 3 not needed

PCA1	Control Output	Power Supply	Input (*1)	Option 1 (*2)	Option 2 (*2)	Option3 (*2)	Specification	
PCA1								
	R						Relay contact: 1a1b	
	S						Non-contact voltage (for SSR drive): 12 V DC±15%	
	Α						Direct current: 4 to 20 mA DC	
		0					100 to 240 V AC (Standard)	
		1					24 V AC/DC	
		<u> </u>	0 —				Multi-range (*1)	
				0			Option 1 not needed	
				1			Serial communication RS-232C	С
				2			Serial communication RS-485	C5
				3			Time signal output	TS
				4			Serial communication RS-232C+Time signal output	C+TS
				5			Serial communication RS-485+Time signal output	C5+TS
					0		Option 2 not needed	
					1		Transmission output (4 to 20 mA DC)	TA
					2		Transmission output (0 to 1 V DC)	TV
						0	Option 3 not needed	
						1	Heating/Cooling control output OUT2 Relay contact output (*3)	DR
						2	Heating/Cooling control output OUT2 Non-contact voltage output (*3)	DS
						3	Heating/Cooling control output OUT2 Direct current output (*3)	DA

(\*1) Thermocouple, RTD, Direct current or DC voltage can be selected by keypad.
(\*2) Only one option can be selected from Option 1, Option 2 and Option 3 respectively.
(\*3) If Heating/Cooling control (DR, DS or DA option) is ordered, Event output EV2 is not available.

### Accessories Sold Separately

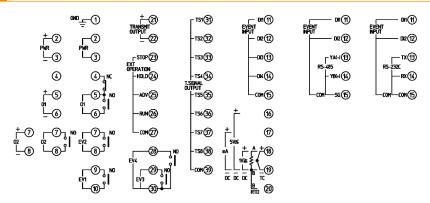
Model
Terminal cover (TC-FCD)
USB communication cable (CMB-001)

# Specifications

	<ul> <li>Thermocouple: K, J, R, S, B, E, T, N, PL-II, C (W/Re5-26) External resistance: 100 Ω max. (However, B: 40 Ω max.)</li> <li>RTD : Pt100, JPt100, 3-wire type, Allowable input lead wire resistance: 10 Ω max. per wire (However, Pt100, -100.0 to 100.0 °C: 5 Ω max. per wire)</li> </ul>
	Direct current : 0 to 20 mA, 4 to 20 mA DC
	Input impedance: 50 $\Omega$ , Allowable input current: 100 mA max.
Input	Direct voltage : 0 to 10 mV DC, -10 to 10 mV DC, 0 to 50 mV DC, 0 to 100 mV DC, 0 to 1 V DC
	Input impedance: 1 M $\Omega$ min., Allowable input voltage: 5 V DC max.
	Allowable signal source resistance: 2 k $\Omega$ max. (0 to 1 V DC), 200 $\Omega$ max.
	(0 to 100 mV DC, 0 to 50 mV DC), 40 Ω max. (-10 to 10 mV DC), 20 Ω max. (0 to 10 mV DC)
	0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	Input impedance: 100 k $\Omega$ min. Allowable input voltage: 15 V DC max.
	Allowable signal source resistance: 100 $\Omega$ max.

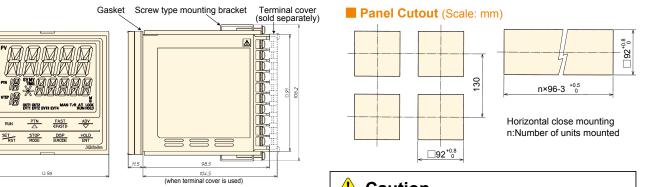
	Thermocouple: Within ±0.2		-					
	However, R, S input, 0 to 200°C (32 to 392°F): Within ±6°C (12°F)							
Desis	B input, 0 to 300℃ (32 to 572°F): Accuracy is not guaranteed. K, J, E, T, N input, Less than 0℃ (32°F): Within ±0.4% of input span ±1 digit							
Basic accuracy				ut span ±1 digit				
		% of each input span ±1	-					
	Direct current : Within ±0.2		•					
In such a second line in a signal	-	% of each input span ±1	aigit					
Input sampling period	125 ms Relay contact 1a1b: Control capacity: 3 A 250 V AC (resistive load), 1 A 250 V AC (inductive load $\cos\phi$ =0.4							
	,	cal life: 100,000 cycles	(Tesistive Ioau), TA250					
		-						
Control output	Non-contact voltage (for SSR drive): 12 V DC±15% Max. 40 mA (short circuit protected)							
	Direct current: 4 to 20 mA	•	·····,					
		ince: Max. 600 Ω						
	Relay contact 1a							
Event output EV1	Control capacity: 3 A 250 V	AC (resistive load), 1 A	250 V AC (inductive load	cosφ=0.4)				
	Electrical life : 100,000 c	cycles						
	Relay contact 1a							
Event output EV2	Control capacity: 3 A 250 V	AC (resistive load), 1 A	250 V AC (inductive load	cos <i>φ</i> =0.4)				
	Electrical life : 100,000 c	cycles						
	Relay contact 1a							
Event output EV3, EV4	Control capacity: 3 A 250 V	AC (resistive load), 1 A	250 V AC (inductive load	cos <i>φ</i> =0.4)				
	Electrical life : 100,000 c	cycles						
	Event output EV3 and EV4		ninal.					
	Number of patterns : 16 (I							
		(16 steps/pattern)						
	Number of repetitions: 0 to 9999 times (Repetitions disabled when set to 0.)							
Program performance	Program time range : 0 to							
Flogram penomiance		en is set: Fixe						
		rmocouple, RTD input wi						
		rmocouple, RTD input wi		.0 to 100.0)°C(°F) le decimal point follows the seled				
		Wait function is disable						
		IA RS-232C (C option), E						
	Communication method : H	,	,					
		•						
	Synchronization method: Start-stop synchronization Communication speed : 9600, 19200, 38400 bps (Factory default: 9600 bps)							
	Data bit : 7 or 8 (Factory default: 7 bits)							
	Parity : E	ven, Odd, No parity (Sel	ectable by keypad) (Fact	ory default: Even)				
	Stop bit : 1	or 2 (Selectable by keyp	ad) (Factory default: 1)					
	Data format:							
Serial communication (optional)	Communication protocol	Shinko protocol	Modbus ASCII	Modbus RTU				
(optional)	Start bit Data bit	1 7	1 7 or 8	8				
			Even (No parity, Odd)	No parity (Even, Odd)				
	Parity	Even	Selectable	Selectable				
	Stop bit	1	1 or 2	1 or 2				
	SV digital transmission: If 'S	•	-	· ·				
	communication, SV can be digitally transmitted to Shinko indicating controllers							
	(with Serial communication C5 option).							
Time signal output		date cycle: 250 ms						
(optional)	Time signal output Number of circuits: 8							
(	Open collector · Canacit	W 24 V DC May 50 mA						
Transmission output	• •	y: 24 V DC, Max. 50 mA						
Transmission output	Resolution : 12000	-						
Transmission output (optional)	Resolution: 12000Output: TA option	: 4 to 20 mA DC (Load re	esistance: Max. 500 Ω)					
	Resolution : 12000 Output : TA option TV option	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re	esistance: Max. 500 Ω) esistance: Min. 100 kΩ)					
	Resolution       : 12000         Output       : TA option         TV option       Output accuracy: Within ±0	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re .3% of Transmission out	esistance: Max. 500 Ω) esistance: Min. 100 kΩ) put span					
	Resolution       : 12000         Output       : TA option         TV option	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re .3% of Transmission out , Event output EV2 will b	esistance: Max. 500 Ω) esistance: Min. 100 kΩ) put span e disabled.	250 V AC (inductive load cosø				
(optional)	Resolution       : 12000         Output       : TA option         TV option	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re .3% of Transmission out , Event output EV2 will b	esistance: Max. 500 Ω) esistance: Min. 100 kΩ) put span e disabled. VAC (resistive load), 1 A	250 V AC (inductive load $\cos\phi$				
(optional) Heating/Cooling control output	Resolution       : 12000         Output       : TA option         TV option	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re .3% of Transmission out , Event output EV2 will b : Control capacity: 3 A 250 Electrical life: 100,000 o	esistance: Max. 500 Ω) esistance: Min. 100 kΩ) put span e disabled. V AC (resistive load), 1 A cycles	250 V AC (inductive load $\cos\phi$				
(optional)	Resolution       : 12000         Output       : TA option         TV option       TV option         Output accuracy: Within ±0       If the D□ option is ordered         Relay contact 1a (DR option)	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re .3% of Transmission out , Event output EV2 will b : Control capacity: 3 A 250 Electrical life: 100,000 c R drive) (DS option): 12	esistance: Max. 500 Ω) esistance: Min. 100 kΩ) put span e disabled. V AC (resistive load), 1 A cycles					
(optional) Heating/Cooling control output	Resolution       : 12000         Output       : TA option         TV option       TV option         Output accuracy: Within ±0       If the D□ option is ordered         Relay contact 1a (DR option)	: 4 to 20 mA DC (Load re : 0 to 1 V DC (Load re .3% of Transmission out , Event output EV2 will b : Control capacity: 3 A 250 Electrical life: 100,000 c R drive) (DS option): 12	esistance: Max. 500 Ω) esistance: Min. 100 kΩ) put span e disabled. V AC (resistive load), 1 A cycles V DC±15% ax. 40 mA (short circuit p					

## Terminal Arrangement



GND	Grounding
PWR	Power supply 100 to 240 V AC or 24 V AC/DC
PWR	For a 24 V AC/DC power source, ensure polarity is correct when using direct current (DC).
01	Control output OUT1
02	Control output OUT2 (DR, DS or DA option)
EV1	Event output EV1
EV2	Event output EV2
EV3	Event output EV3
EV4	Event output EV4
EVENT INPUT	Event input
RS-485/RS-232C	Serial communication RS-485 (C5 option) or RS-232C (C option)
TC	Thermocouple input
RTD	RTD input
DC 1V≧	DC voltage input: 0 to 10 mV DC, -10 to 10 mV DC, 0 to 50 mV DC, 0 to 100 mV DC, 0 to 1 V DC
DC 5V≦	DC voltage input: 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
DC mA	Direct current input: 0 to 20 mA DC, 4 to 20 mA DC
TRANSMIT OUTPUT	Transmission output (TA or TV option)
EXT OPERATION	External operation input: STOP, HOLD, ADV, RUN
T.SIGNAL OUTPUT	Time signal output (TS option)

## External Dimensions (Scale: mm)



Caution

If horizontal close mounting is used for the controller, Drip-proof/Dust-proof IP66 may be compromised, and all warranties will be invalidated.

> Caution with respect to Export Trade Control Ordinance

To avoid this instrument from being used as a To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this

instrument is not illegally exported

- To ensure safe and correct use, thoroughly read and understand the manual before using this instrument. This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify
- This instrument is interface to be depiced on inducting interface, interface on a finite state interface on the state of t as malfunction of this product could result in serious damage to the system or injury to personnel. Also proper periodic maintenance is required.
  - This instrument must be used under the conditions and environment described in the manual. Shinko Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

This catalog is as of May 2018 and its contents are subject to change without notice.

- · Photos used in this catalog do not show unit in operating status.
- . If you have any inquiries, please consult us or our agency.

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SAFETY

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